

Fig. 1



Fig. 2A

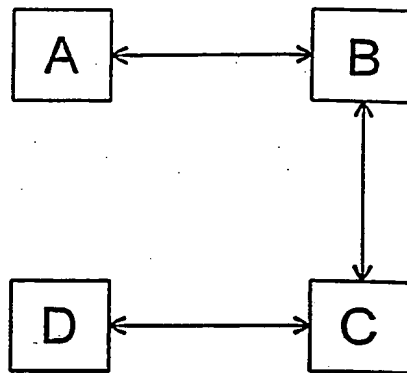


Fig. 2B

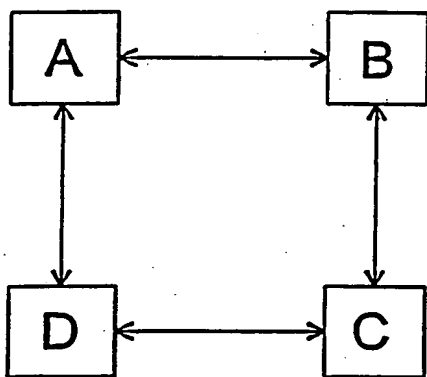


Fig. 2C

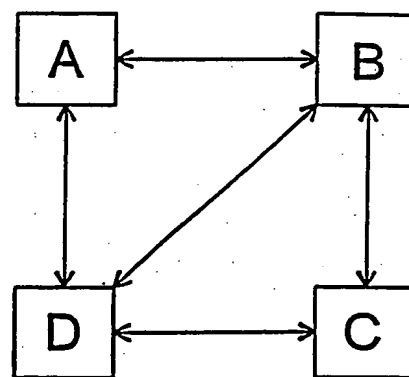


Fig. 2D

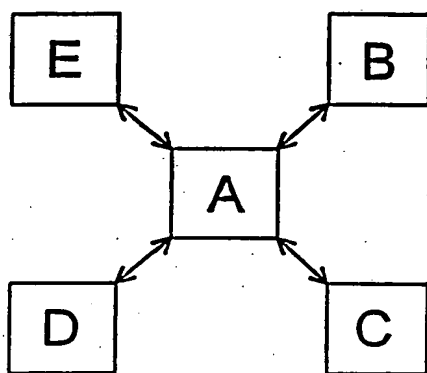


Fig. 2E

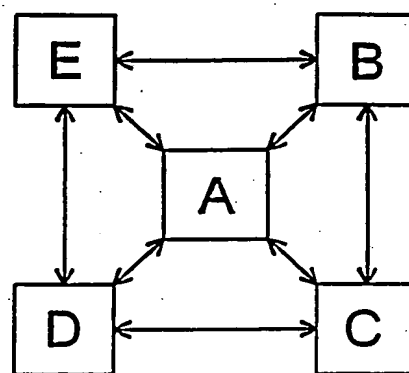


Fig. 2F

100

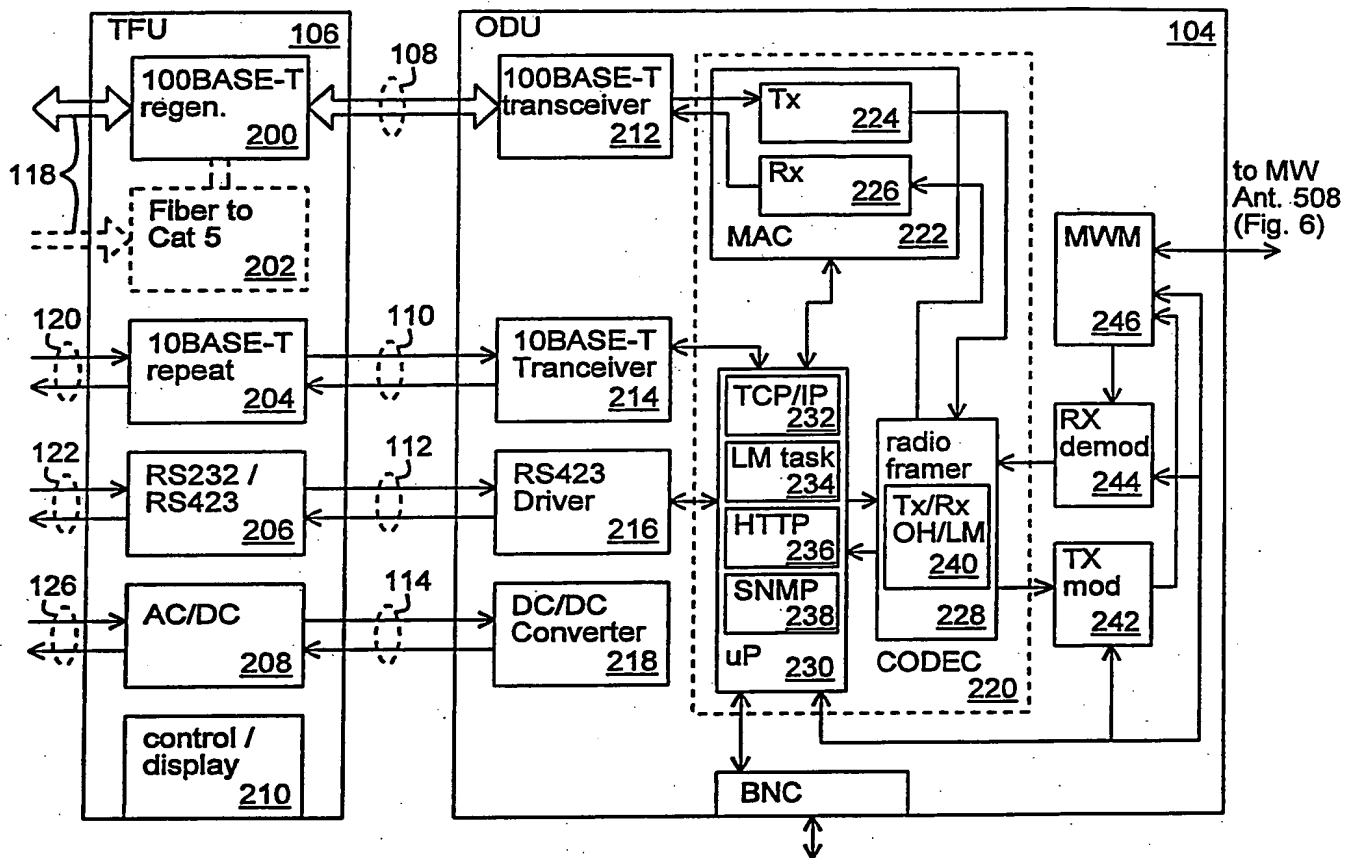


Fig. 3

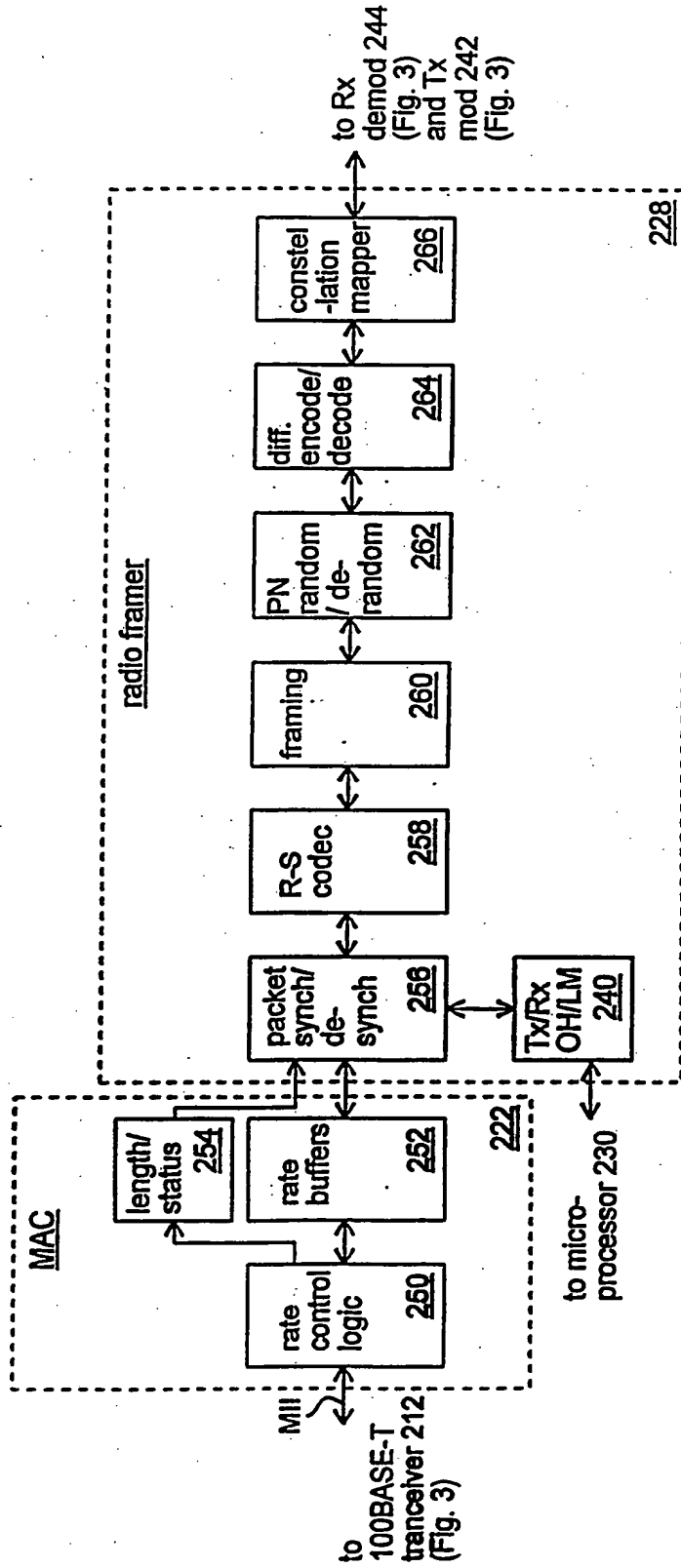


Fig. 4



300 →

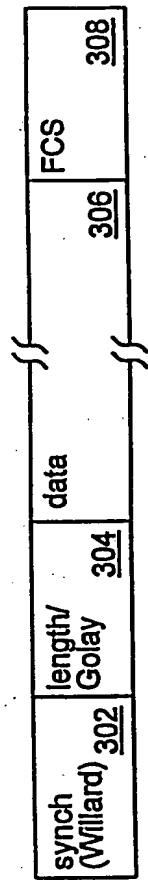


Fig. 5



350 ↗

synch	<u>352</u>	aux	<u>354</u>	data	<u>356</u>	R-S parity	<u>358</u>
-------	------------	-----	------------	------	------------	------------	------------

Fig. 6

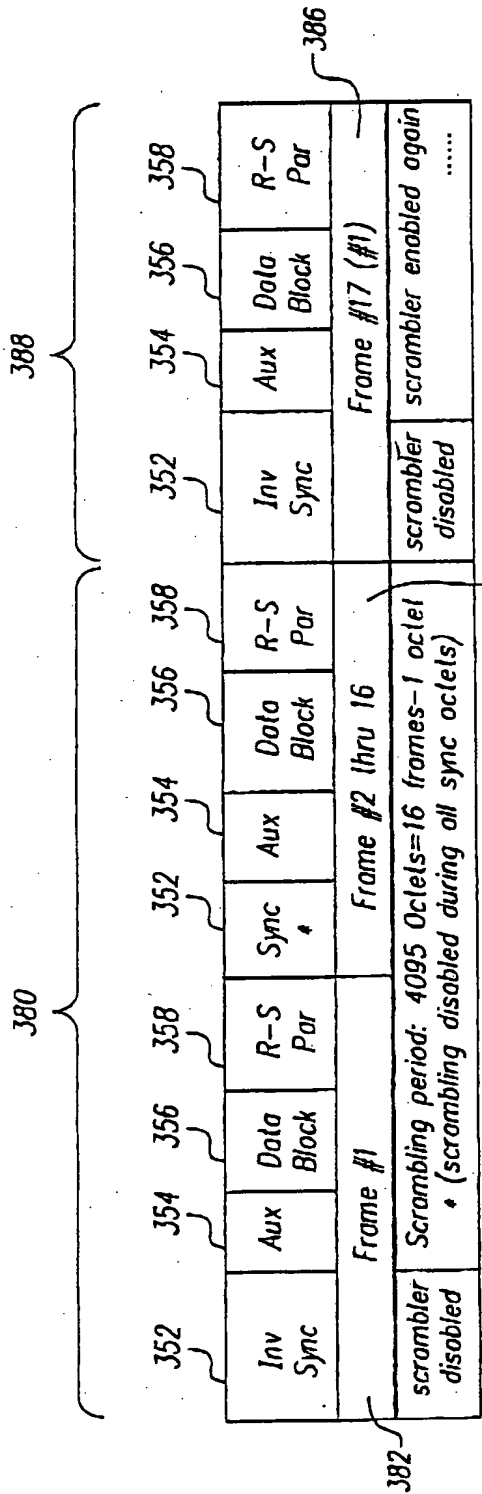


FIG. 7

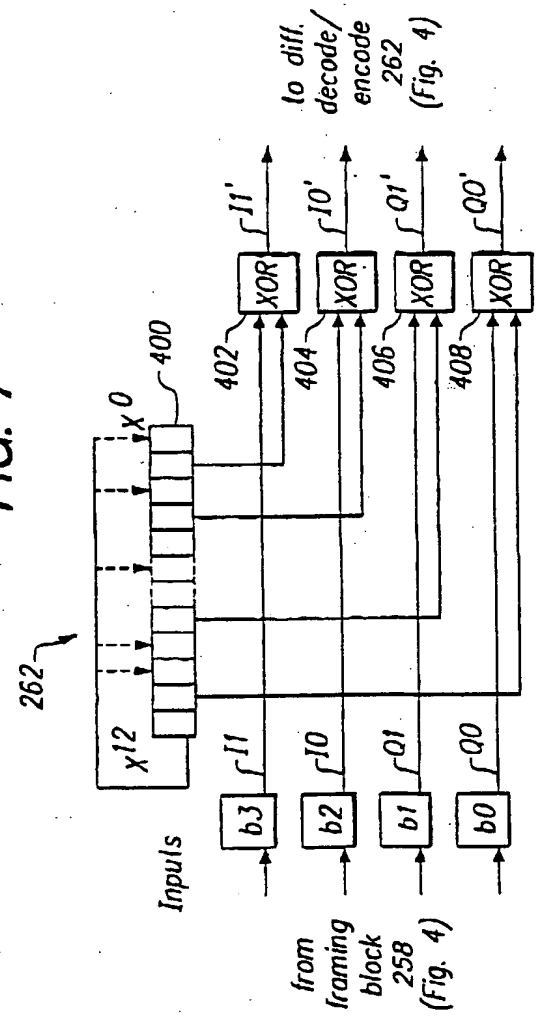


FIG. 8

$Quad = 2 \cdot I1' + Q1'$ ;      - Map Quadrant Tag [0 1 2 3]  
 $Phi = [0 \ 1 \ 3 \ 2]$ ;      - to Angle = [0 1 2 3]  
 $Angle = Phi(Quad)$   
 $Sum = (Sum + Angle) \text{ modulo } 4$ ;  
 $I1'' = \text{bit 1 of Sum}; \quad I0'' = I0'$ ;  
 $Q1'' = \text{bit 0 of Sum}; \quad Q0'' = Q0'$ ;

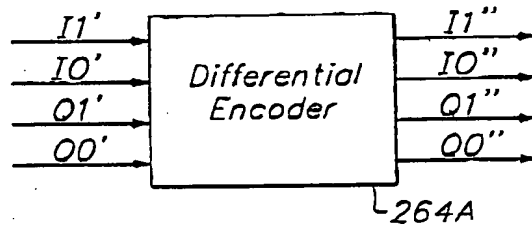


FIG. 9

$Angle = 2 \cdot RxIs' + RxQs'$ ;  
 $Phi' = [0 \ 1 \ 3 \ 2]$ ;  
 $Diff = (Phi'(Angle) - Phi_0) \text{ modulo } 4$ ;  
 $Phi_0 = Phi'(Angle)$ ;  
 $RxIs = \text{bit 1 of } Phi'(Diff); \quad RxIm = RxIm'$ ;  
 $TxIs = \text{bit 0 of } Phi'(Diff); \quad RxQm = RxQm'$ ;

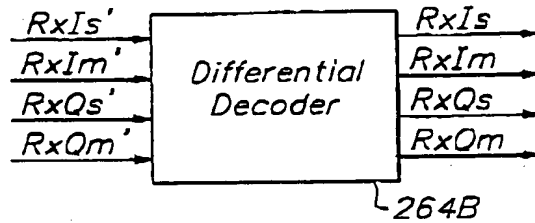


FIG. 10



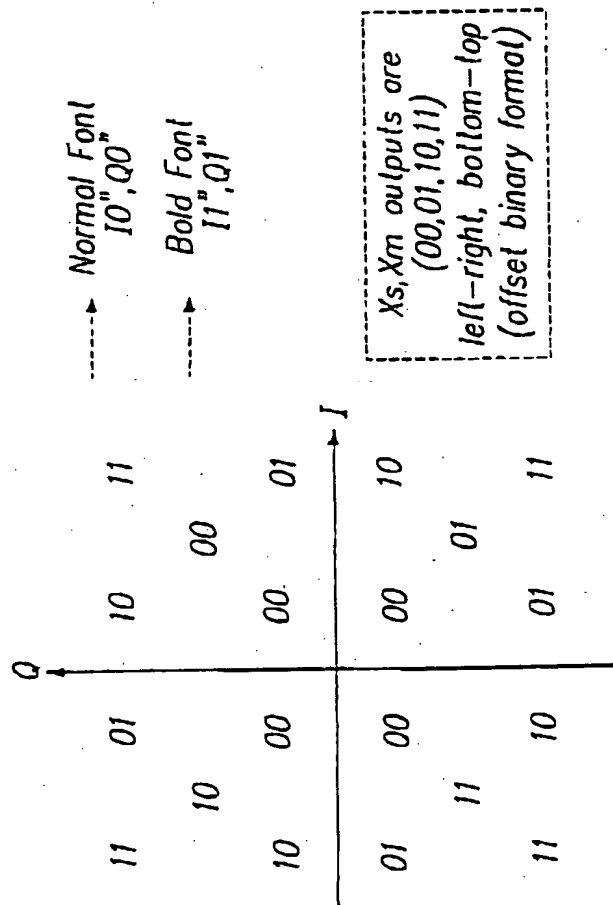


FIG. 11

Input Symbols  
 Shown in Output  
 Symbol Position

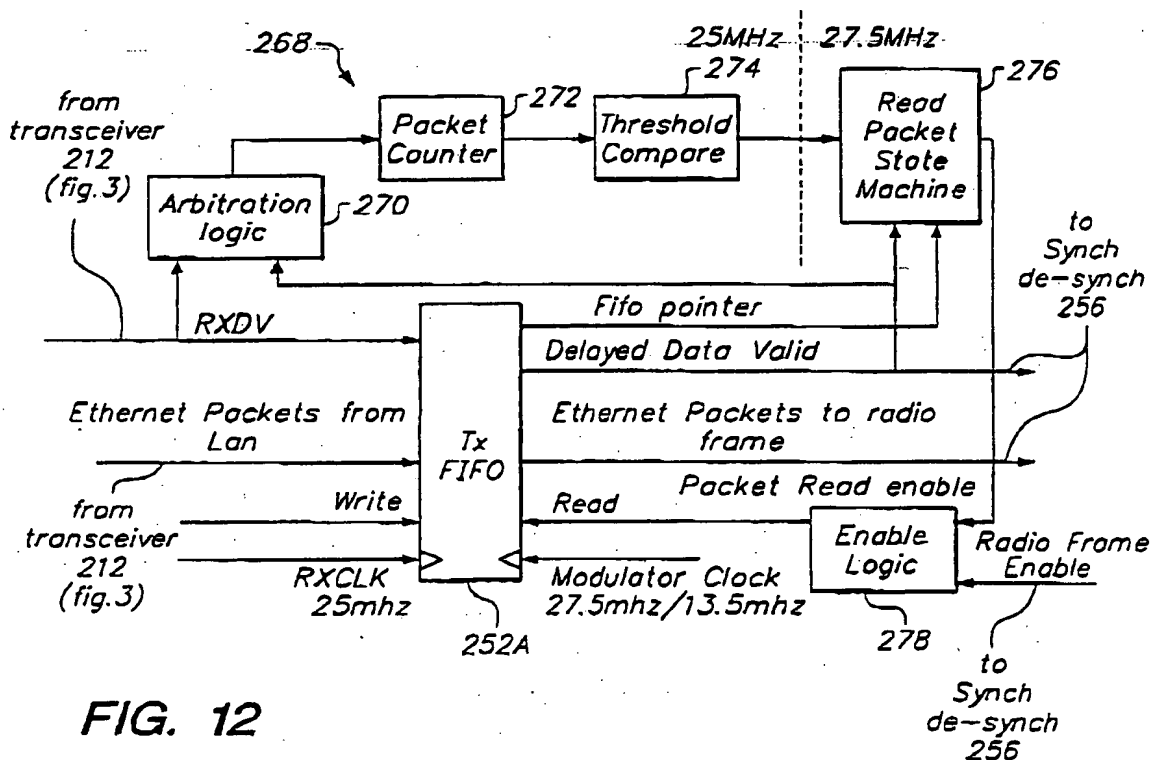


FIG. 12

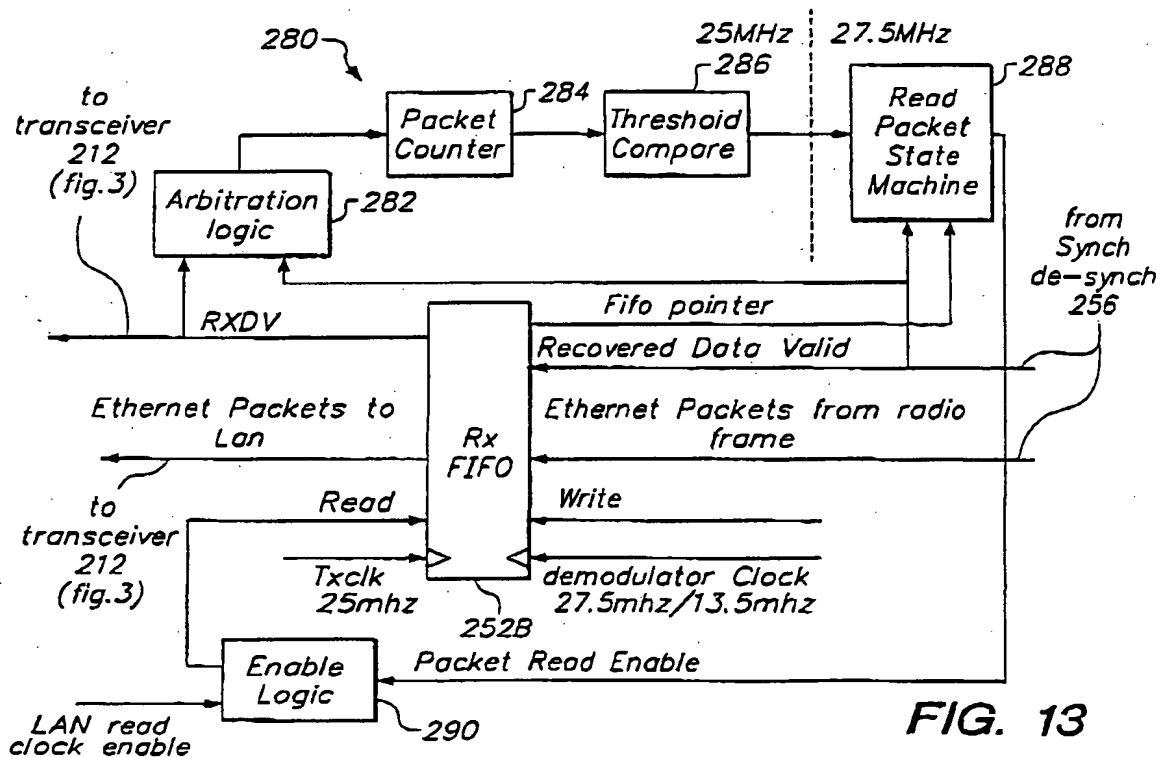


FIG. 13

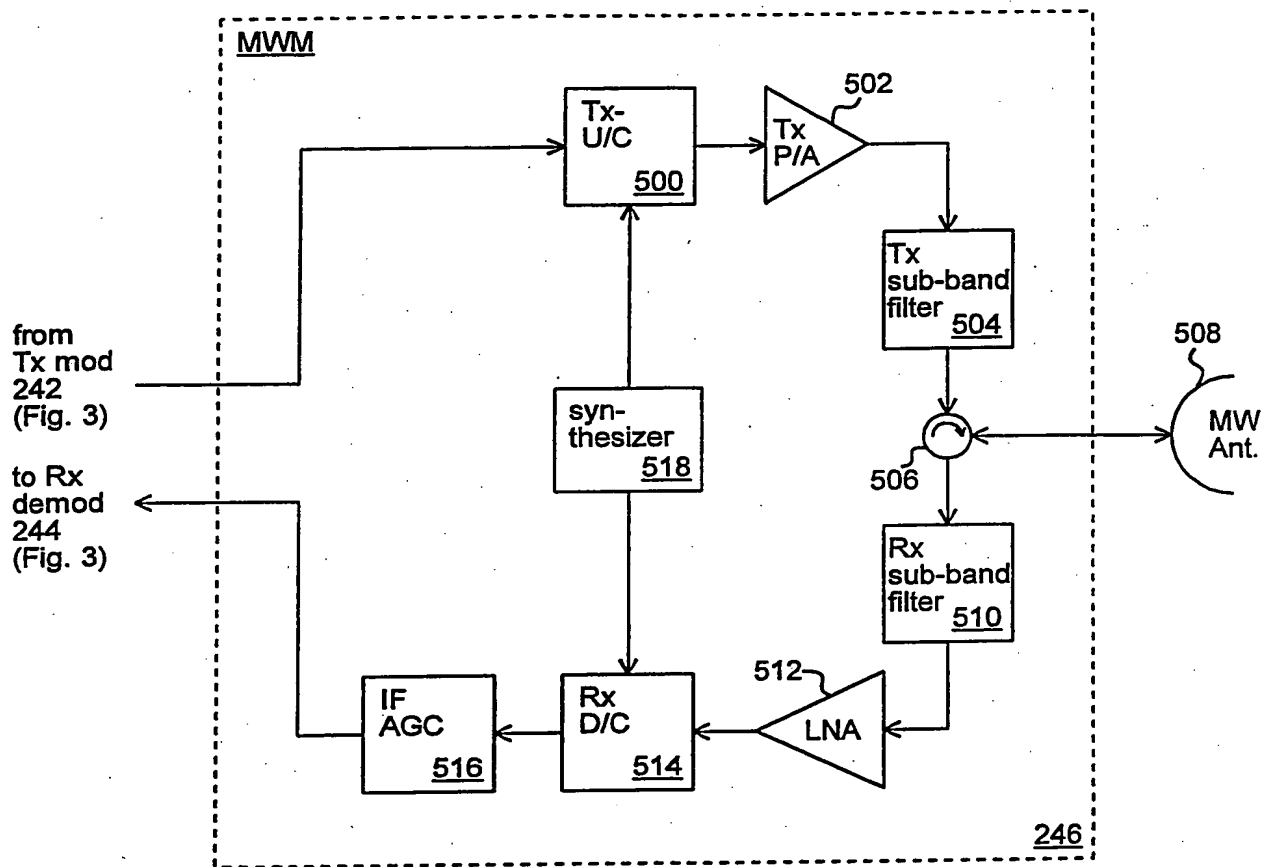


Fig. 14

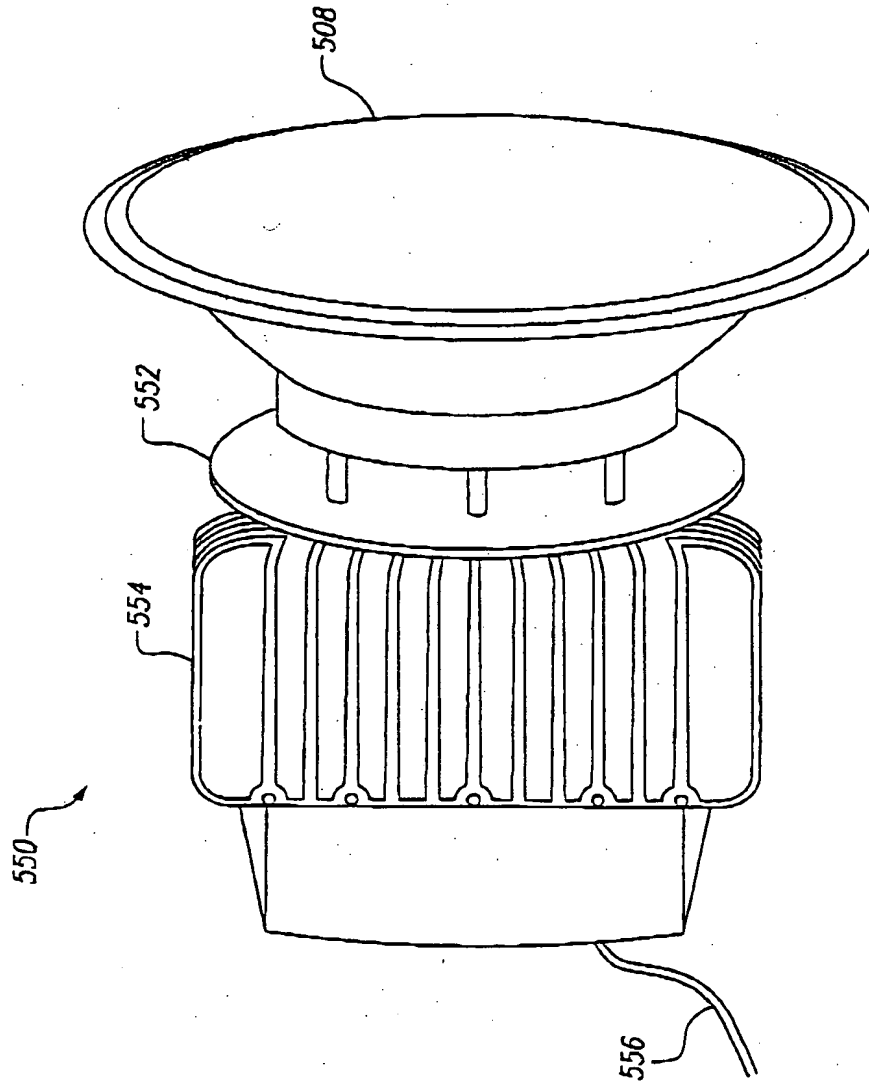


FIG. 15

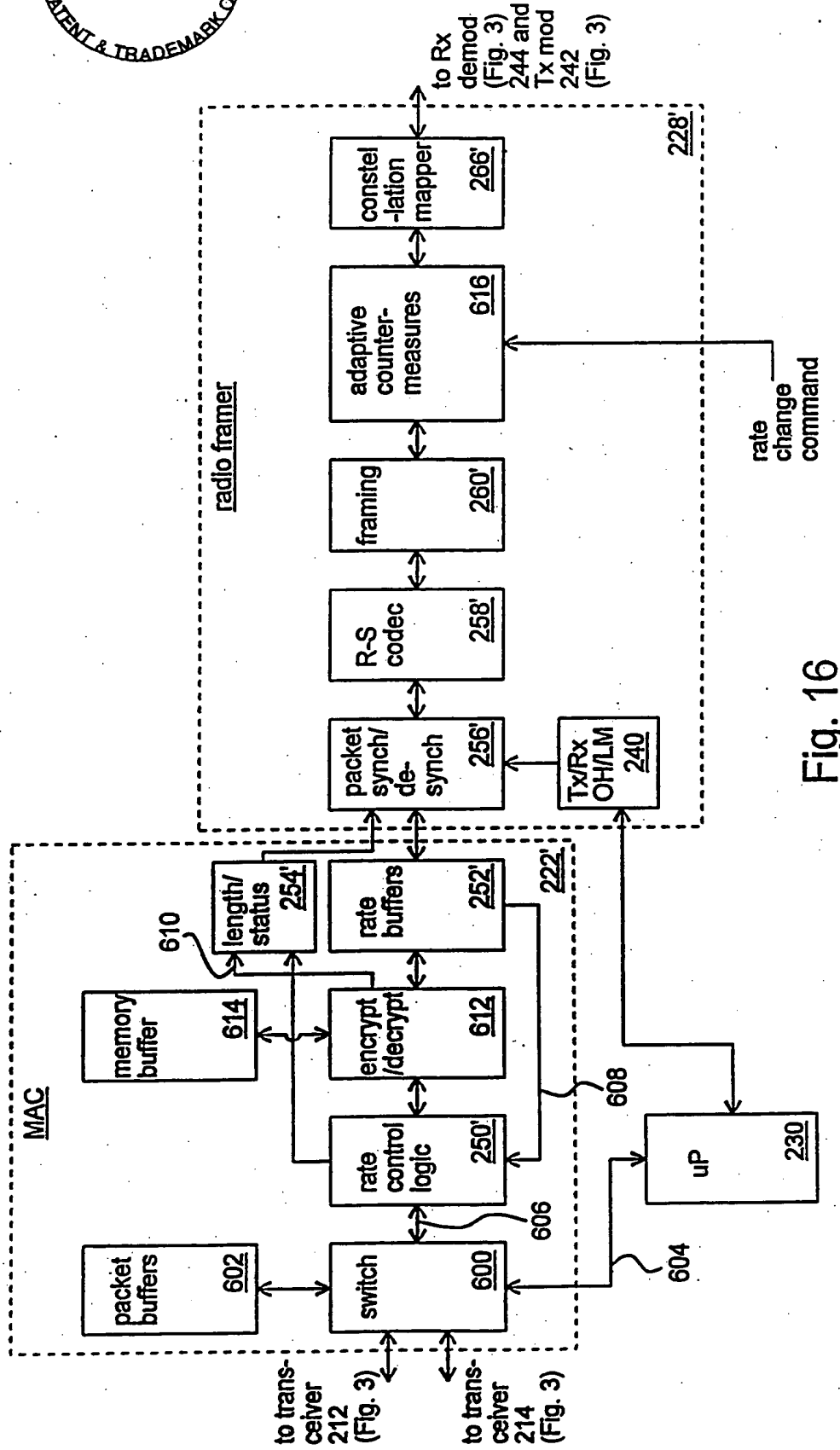


Fig. 16

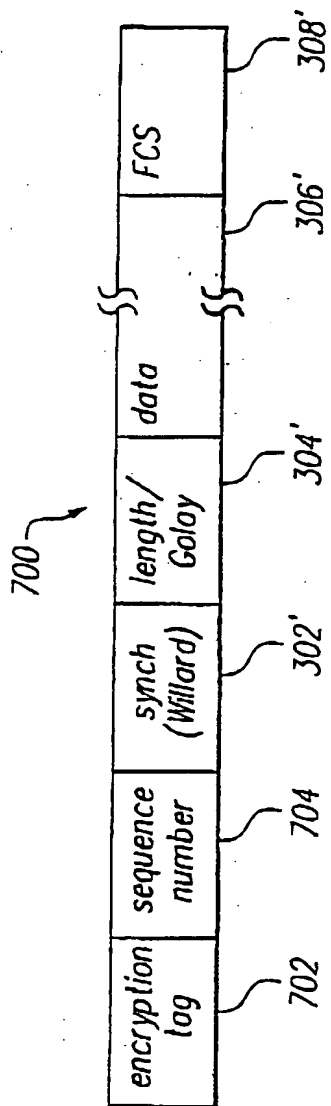
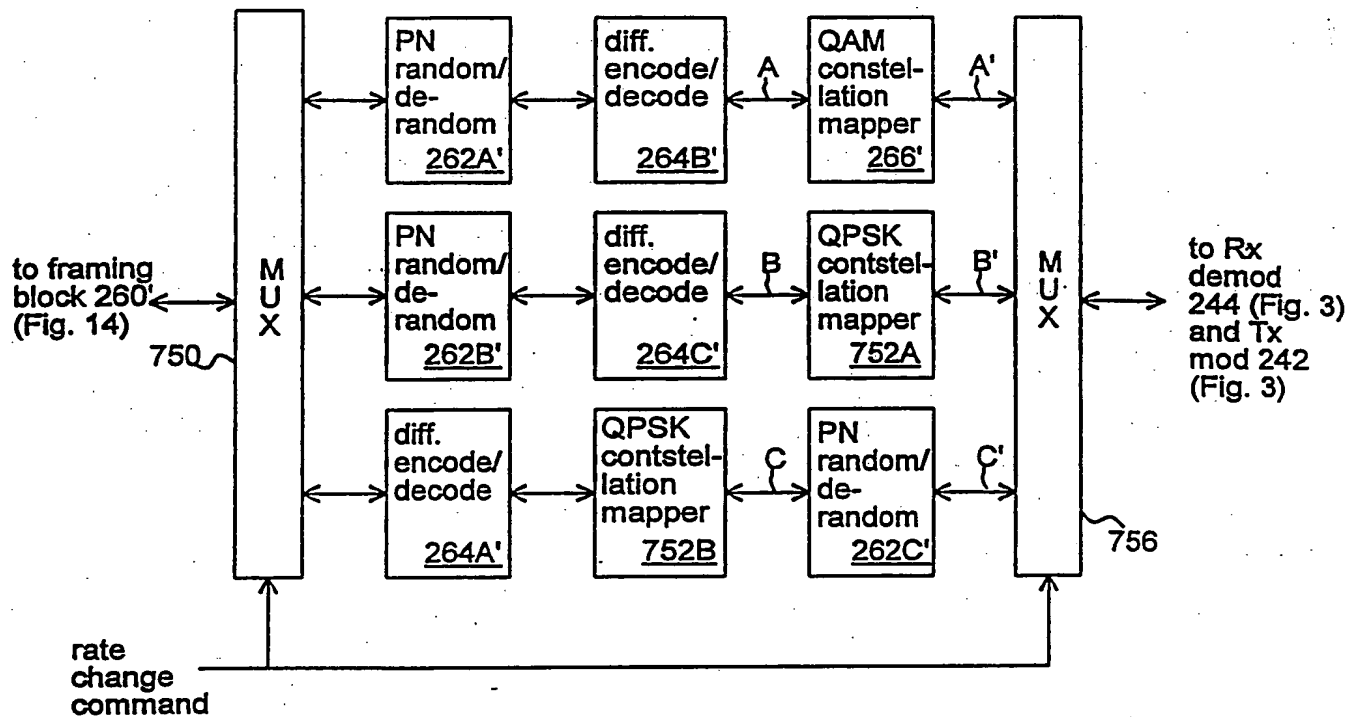


FIG. 17



616



A: data rate = 4 bits/symbol, symbol rate = 27.5 Msymbols (mega-symbols)/second

A': data rate = 4 bits/symbol, symbol rate = 27.5 Msymbols/second

B: data rate = 2 bits/symbol, symbol rate = 27.5 Msymbols/second

B': data rate = 2 bits/symbol, symbol rate = 27.5 Msymbols/second

C: data rate = 2 bits/symbol, symbol rate = 3.4375 Msymbols/second

C': data rate = 2 bits/symbol, symbol rate = 27.5 Msymbols/second

Fig. 18

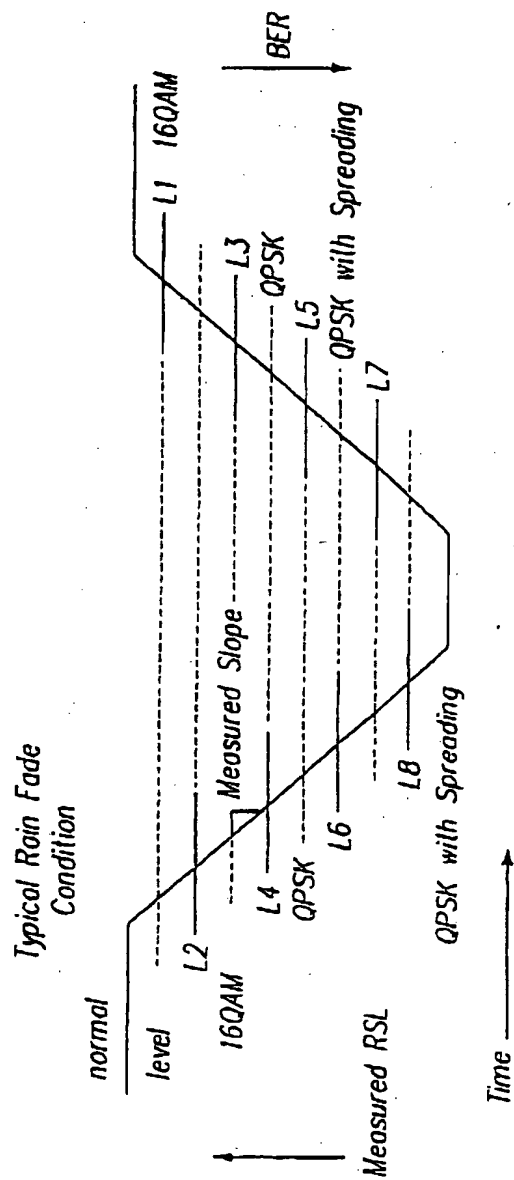


FIG. 19



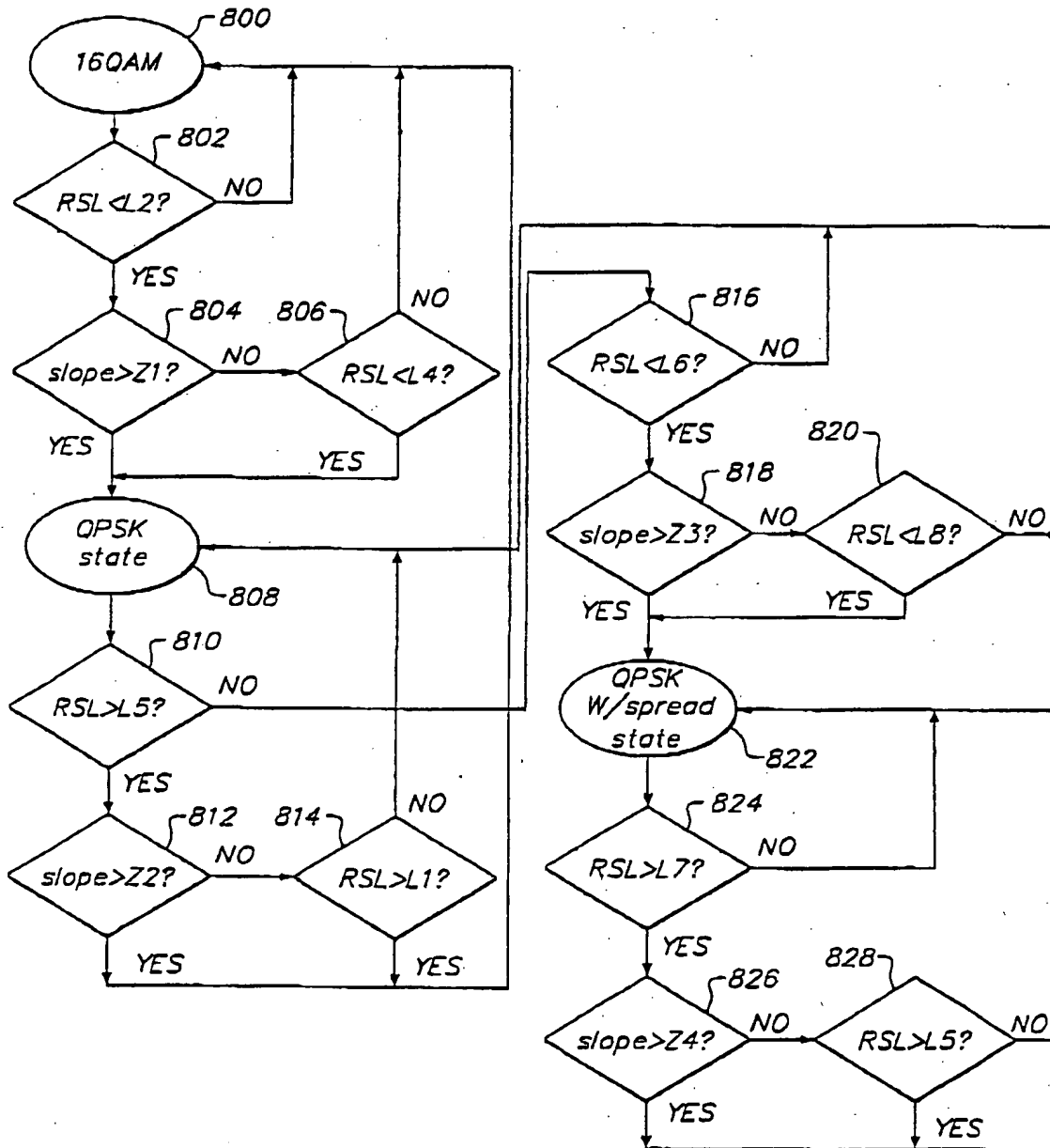


FIG. 20

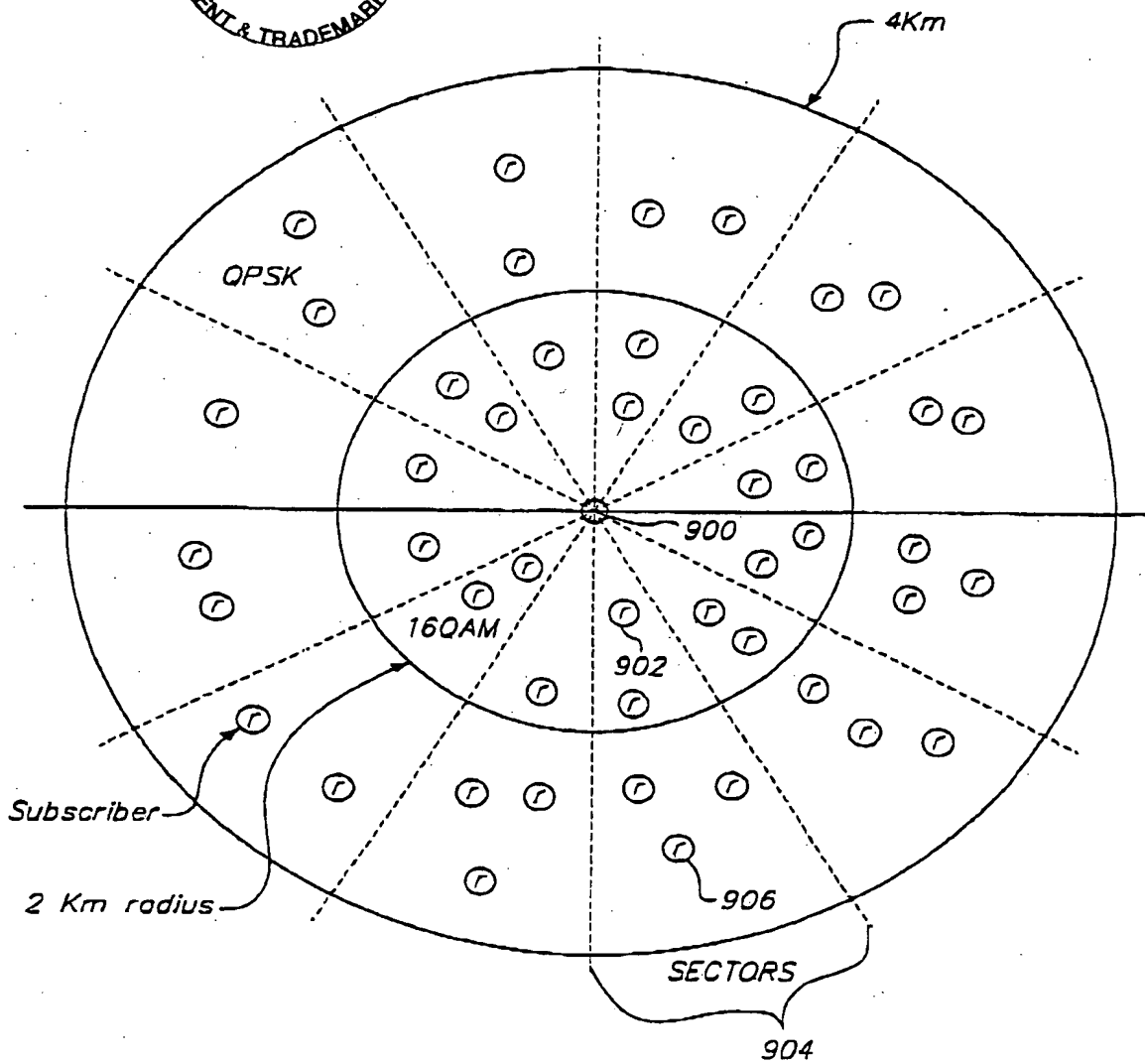


FIG. 21

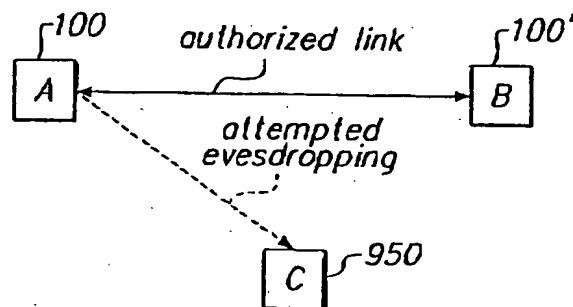


FIG. 22